

WEST Search History

[Hide Items](#)[Restore](#)[Clear](#)[Cancel](#)

DATE: Wednesday, March 17, 2004

Hide?	<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>
		<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>	
<input type="checkbox"/>	L2	(data or datum or instruction or command or preset or "pre-set") and L1	67
<input type="checkbox"/>	L1	emotion same model and detection and storage and pressure	67

END OF SEARCH HISTORY

A study of a method for intention inference from human's behavior*Inagaki, Y.; Sugie, H.; Aisu, H.; Unemi, T.;*

Robot and Human Communication, 1993. Proceedings., 2nd IEEE International Workshop on , 3-5 Nov. 1993

Page(s): 142 -145

Behavior modeling of uncertain dynamic systems with nonlinearity*Qunhua Tan; Wei Li;*

TENCON '96. Proceedings. 1996 IEEE TENCON. Digital Signal Processing Applications , Volume: 2 , 26-29 Nov. 1996

Page(s): 731 -736 vol.2

A concurrent, object-oriented implementation for the tactical level of the rational behavior model software architecture for UUV control*Se-Hung Kwak; Thornton, F.P.B., Jr.;*

Autonomous Underwater Vehicle Technology, 1994. AUV '94., Proceedings of the 1994 Symposium on , 19-20 July 1994

Page(s): 54 -60

Fuzzy adaptation impedance of a 6 DOF parallel robot: application to peg in hole insertion*Babaci, S.; Amirat, Y.; Pontnau, J.; Francois, C.;*

Fuzzy Systems, 1996., Proceedings of the Fifth IEEE International Conference on , Volume: 3 , 8-11 Sept. 1996

Page(s): 1770 -1776 vol.3

A novel approach to smooth trajectory planning of a mobile robot*Aydin, S.; Temeltas, H.;*

Advanced Motion Control, 2002. 7th International Workshop on , 3-5 July 2002

Page(s): 472 -477

Direct brain stimulation enables training of complex behaviors in freely roaming animals*Talwar, S.K.; Xu, S.; Hawley, E.S.; Moxon, K.A.; Chapin, J.K.;*

[Engineering in Medicine and Biology, 2002. 24th Annual Conference and the Annual Fall Meeting of the Biomedical Engineering Society] EMBS/BMES Conference, 2002. Proceedings of the Second Joint , Volume: 3 , 23-26 Oct. 2002

Page(s): 2076 -2077 vol.3

Proceedings of the 32nd Midwest Symposium on Circuits and Systems (Cat. N .89CH2785-4)

Circuits and Systems, 1989., Proceedings of the 32nd Midwest Symposium on , 14-16 Aug. 1989

Autonomous robots and emergent behavior: a set of primitive behaviors for mobile robot control*Anderson, T.L.; Donath, M.;*

Intelligent Robots and Systems '90. 'Towards a New Frontier of Applications', Proceedings. IROS '90. IEEE International Workshop on , 3-6 July 1990

Page(s): 723 -730 vol.2

A distributed control architecture for a purposive computer vision system*Bianchi, R.A.C.; Rillo, A.H.R.C.;*

Intelligence and Systems, 1996., IEEE International Joint Symposia on , 4-5 Nov. 1996

Page(s): 288 -294

A FPGA-based behavioral control system for a mobile robot

Kongmunvattana, A.; Chongstivatana, P.;

Circuits and Systems, 1998. IEEE APCCAS 1998. The 1998 IEEE Asia-Pacific Conference on , 24-27 Nov. 1998

Page(s): 759 -762

Missile control with the UML and SDL formalisms

Champeau, J.; Dhaussy, P.; Latreille, L.;

OCEANS 2000 MTS/IEEE Conference and Exhibition , Volume: 3 , 11-14 Sept. 2000

Page(s): 1639 -1645 vol.3

Multilevel multi-agent based team decision fusion for mobile robot behavior control

Tse Min Chen; Luo, R.C.;

Intelligent Control and Automation, 2000. Proceedings of the 3rd World Congress on , Volume: 1 , 28 June-2 July 2000

Page(s): 489 -494 vol.1

Supervised control of cooperative multi-agent robotic vehicles

Shirikhodaie, A.;

System Theory, 2002. Proceedings of the Thirty-Fourth Southeastern Symposium on , 18-19 March 2002

Page(s): 386 -390

Reaction-diffusion CNN algorithms to generate and control artificial locomotion

Arena, P.; Fortuna, L.; Branciforte, M.;

Circuits and Systems I: Fundamental Theory and Applications, IEEE Transactions on , Volume: 46 Issue: 2 , Feb. 1999

Page(s): 253 -260

Copyright © 2003 IEEE -- All rights reserved